



Quantitative Risk Analysis for Communication Satellite Payload

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ABSTRACT

The application of risk management is a critical stage for any spacecraft project to achieve required components and system functionality for a successful mission, a risk management plan is high-level accounts and descriptions of risk concepts for any satellite mission to be successful. This research article investigates the application of criticality analysis and risk priority number analysis for communication satellite payload components by following industry standard and using MIL-STD-1628, MIL-STD-1629A termed as military standard and the ECSS-Q-STD-30-02C termed as European Cooperation for Space Standardization for space product assurance in conducting analysis of risk and determining mitigation techniques and also determined the sample correlation coefficient of criticality of components and risk priority.

Keywords: Correlation, Payload, Project, Risk, Satellite.

1 INTRODUCTION

The utilization of space technologies has increased substantially, bringing with it, a share of benefits, ranging from early environment and disaster threat detection and warnings, climatic changes, metrological forecasts, geographical information system (GIS), as well as enhanced communication (Spagnulo, 2013). A satellite system performs these multifaceted functions because of its design which consist of two functional areas, the Bus Systems and the Communication Payload Systems as in figure 1 and figure 2 respectively.

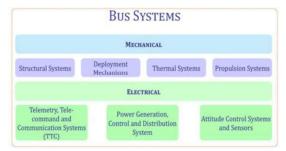
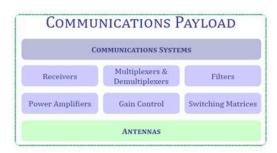
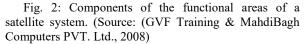


Fig. 1: Components of the functional areas of a satellite system. (Source: (GVF Training & MahdiBagh Computers PVT. Ltd., 2008)





While the Bus system consists of all the elements that support the communication payload, the communication payload provides support for all the functional aspects of the mission for which the satellite is launched (GVF Training & MahdiBagh Computers PVT. Ltd., 2008)

The increased utilization of space technologies necessitated an increased need for space research and explorations. Consequently, satellites are launched into space for either communication or environmental monitoring for disaster. Satellites have different functionalities, determined by their locations in space. Excerpts from existing literature (Braun, 2012; Stanniland & Curtin, 2013) suggest that Low Earth Orbit (LEO) satellites are used for navigation, space missions, and low latency communication, the Medium Earth Orbit (MEO) satellites, while performing the same function as the LEO satellites, are differentiated by the distance from the earth, and the Geostationary (GEO) satellites are commonly used for communication purposes.





Satellite has been recognised as driver for national growth and sustainable development, access to reliable and adequate geospatial information (GI) according to Akinyede and Agbaje (2006). The recognition of this fact, may have prompted the Nigerian government to initiate moves, the NIGCOMSAT-1, a Nigerian Communication Satellite Project (Zhicheng et al., 2006), aimed at addressing the problem of communication, seen as one of the greatest setbacks to the socio-economic development of the country, particularly in the areas of rural telephoning, broadcasting, tele-education, telemedicine, e-government, e-commerce and real-time monitoring services (Chukwu-Okoronkwo, 2015). Boroffice (2008) noted that the NigComSat-1 project was to provide a platform for capacity-building and the development of satellite technology for the level of transformation in the telecommunication, broadcasting and broadband industry in Africa, as well as prospects increased businesses in rural and remote regions through access to strategic information.

Although the contribution of satellite systems has been substantial, Bargellini and Edelson (1977) noted that satellite communications systems will continue to expand because traffic growth forecasts indicate the need for greater communications capacity. Consequently, the financing of communications satellite has grown from a government organised, privately operated venture, to regulated and competitive part of the economic infrastructure. However, one critical factor confronting the satellite communication industry is the risk of damage, resultant disruption to service and liabilities due to collision as result of derelict satellite (Pelton et al., 2017).

The planning, building, launching, financing, and operating a communication satellite is a routine business for long term investment and its require a high up-front capital expenditure with a start-up period of 2 years, with a large number of high investment risk factors (Pelton et al., 2017). The effect of a satellite failure, in terms of cost and multiplier effect is huge, as noticeable in Zhicheng et al. (2006) containing an account of the failed NIGCOMSAT-1, which was de-orbited due to Electrical Power Subsystems defect in the Solar Array Drive Assembly (SADA), and replaced with NIGCOMSAT-1R.

The risk and cost associated with satellite failures like the NIGCOMSAT-1 is huge and by far outweighs the cost of carrying out a risk assessment of the space project. In the NIGCOMSAT-1 failure cited above, although the satellite was replaced at no cost to the Nigerian government, there were chances of collision with other satellite in the adjacent orbital slot when if it were not deorbited. Even with the de-orbiting, the resulting space debris posed another risk for other satellites in orbit. To avert all these risk factors, the need for adequate and thorough risk analysis of critical components and risk priority analysis before satellite launch become crucial.

Fales (1984) observes that given the fact that the development and production programme for satellite communications terminals are affected by a variety of risks from both satellite and terminal development, an understanding of the effect and impact of these risks on the terminals becomes a crucial step towards mitigating the overall system risk. Risk analysis of a communication satellite should provide an insight into risk areas with a view to designing a good mitigation strategy, identify areas where management reserve can be committed early to risk reduction activities, and determine the appropriate level of management reserve (Fales, 1984), as shown in table 1.

Inferences from existing studies is that the above, requires the development of a risk management plan to take account of risks by identifying, and conducting analysis, following the root cause of each risk and the consequences of each risk and providing mitigating plans (Gamble, 2015; Gamble & Lightsey, 2014; Gamble & Lightsey, 2015; Gamble & Lightsey, 2016)

TABLE 1: STEPS IN RISK MANAGEMENT PLAN

Main Step	Sub-steps			
A.Risk	1.Review the mission concept of			
identification	operation			
	2.Identify root causes			
	3.Classify priority of risk			
	4.Name responsible person			
	5.Rank likelihood (L) and			
	consequence(C) of root cause			
	6.Describe rationale for ranking			
	7.Compute mission risk likelihood			
	and consequence values			
	8.Plot mission risks on L-C chart			
B.Determine	1.Avoid the risk by eliminating			
mitigation	root cause and/or consequence			
techniques	2.Control the cause or			
	consequence			
	3.Transfer the risk to a different			
	person or project			
	4.Assume the risk and continue in			
	development			
C. Track progress	Plot the mission risk values on an			
	L-C chart at life-cycle or design			
	milestones to see progress			

Table 1: Steps of Risk Management Plan. Source: Gamble (2015)





A risk may be assessed either qualitatively or quantitatively. Risk management process utilizes rating scales for each of the risk factors with impact, likelihood, and time frame (National Research Council (U.S.), 2005). The impact of a risk event can be to cost, schedule and technical performance. Qualitative risk assessment provides relative values of the likelihood of occurrence and potential consequences of each risk, in general qualitative risk assessment method would be adequately for making risk management decision. Quantitative risk assessment which is usually undertaken for high, critical, or unmanageable risks as determined through the qualitative risk assessment is aimed at establishing the amount of contingency to be included in the estimate for the risks undergoing this assessment, such that should the risk(s) occur, there would be sufficient budgeted amount to overcome the extra expenditure (Srinivas, 2019). This is possibly because quantitative methods require more precise analyses and understanding of the risk or allocation of resources for risk reduction (GOES, 2013).

Although Meyer (2015) notes that quantitative risk analysis is less common in risk management of projects due to insufficient data about the project to perform this analysis of risk quantitatively, the practice of quantitative risk methods would be appropriate to the schedule, budget and risk forbearance of communication satellite mission and will result in more informed knowledge and more successful communication satellite missions.

The results from quantitative risk and reliability analysis were an important input into decision making during design process. These results provided ways to compare relative risks and to inform the decision makers. Key programmatic decisions that were influenced by the risk assessment results in the satellite industry include; choice of Crew Launch Vehicle (CLV), choice of propulsion system, choice of lunar mission mode, elimination of unnecessary radiation shield and definition of acceptable risk in a space mission.

However, the approach for this work was to contribute to the risk analysis of communication payload in order to make improvement in the payload system under analysis, which was based on reliability of the payload components by combining both criticality and risk priority number analysis compared to other works which were based on quality, safety, control or depending on the purpose for the FMEA. By including the quantitative risk assessment into the design process effectively blend the performance and risk within time and budget constraint were achieved (Dale, 2005).

2 METHODOLOGY

This research utilized both qualitative and quantitative research approaches. A purposive sampling, a nonprobability sampling technique, that focuses on a particular characteristics of a population of interest, thus enabling answers to research questions. Team of engineers from different background in satellite industry participated to come up with the decision on the parameters of the Risk Priority Number (RPN) of each component. Tables related to each of these parameters can be found in the associated standards (ECSS-Q-ST-30-02C, 2009) (European Cooperation for Space Standardization (ECSS), 2009).

Table 2 shows the charting of failure effects severity to the performance of a satellite communication payload. "Severity classification category shall be assigned to each failure mode and component according to the failure effect.

TABLE 2: THE FOUR SEVERITY LEVELS OFFAILURE AS DEVELOPED BY MIL-STD-1628

Cat	Effect	Criteria		
egory				
4	Catastrophic	Failure mode capable of		
		causing complete components,		
		system and mission lost.		
3	Critical	Failure mode capable of		
		component damage, system		
		degradation that could reduce		
		the performance of the		
		components or the system.		
2	Major	Failure that could cause		
		components damage, system		
		damage that are not critical. It		
		will lead to delay or loss of		
		availability.		
1	Minor	Failure that would not		
		cause components damage,		
		system degradation but could		
		lead to unscheduled		
		maintenance.		





2.1 FAILURE MODE EFFECT CRITICALITY ANALYSIS (FME(C) A) APPLICATIONS FOR COMMUNICATION SATELLITE PAYLOAD

In line with the FMEA procedures of identifying the failure modes for each components of the system, it was essential to itemize failure modes for each component after decomposing the system into block diagram. The system design, assembly, and installation can provide the information needed for the failure modes for each unit component of the system (Harland & Lorenz, 2007).

The effect on the functional condition of the component under analysis caused by the loss or degradation of output shall be identified so the failure mode effect will be properly categorized" (MIL-STD-1629A, 1980) (Department of Defense United States of America, 1980).

Quantitative risk analysis data shortage gave room for organizations to come up with standards of requirement to meet up their needs, the military standard 1628 term as MIL-STD- 1628. (Liu at el 2013) came up with some ratings on failure occurrence, detection and severity as in table 3, table 4 and table 5 respectively below. These tables are used for computing and analysing the failure mode severity, occurrence and detection for the communication payload components risk analysis.

TABLE.3: SUGGESTED RATINGS FOR THE OCCURRENCE OF A FAILURE MODE

Probability of failure	Possible failure rates	Rank
Nearly	≤ 1 in 150,000	1
impossible		
Remote	1 in 150,000	2
Low	1 in 15,000	3
Relatively low	1 in 2000	4
Moderate	1 in 400	5
Moderately high	1 in 80	6
High	1 in 20	7
Repeated failures	1 in 8	8
Very high	1 in 3	9
Extremely	≥ 1 in 2	10
high(failure		
almost		
inevitable)		

Adapted from (Liu et al., 2013)

TABLE 4: SUGGESTED RATINGS FOR THE SEVERITY OF A FAILURE MODE.

Effect	Severity of	Rank
2	effect	
None	No effect	1
Very minor	Very minor	2
	effect on product	
	or system	
	performance	
Minor	Minor effect on	3
	product or	
	system	
Τ	performance	4
Low	Small effect on	4
	product	
	performance. The product does	
	not require repair	
Moderate	Moderate effect	5
Intodefate	on product	
	performance.	
	The product	
	requires repair	
Significant	Product	6
C	performance is	
	degraded.	
	Certain functions	
	may not operate	
Major	Product	7
	performance is	
	severely affected	
	but functions.	
	The system may	
Extreme	not operate Product is	8
Extreme	Product is inoperable with	0
	loss of primary	
	function. The	
	system is	
	inoperable	
Serious	Failure involves	9
	hazardous	
	outcomes and/or	
	noncompliance	
	with government	
	regulations or	
	standards	
Hazardous	Failure is	10
	hazardous, and	
	occurs without warning. It	
	suspends operation of the	
	system and/or	
	involves	
		L





	noncompliance					otential	
	with government				use of fail		
	regulations				bsequent	failure	
					ode		
Adapted from (Liu	1 et al., 2013)		Very remo		ery remote)
					e design cont		
						otential	
					use of fail		
	TED RATINGS FOR THE DET	TECTION OF A		su	bsequent	failure	
FAILURE MODE					ode		
	T		Absolute		esign contro		0
Detection	likelihood of	Rank	uncertainty		t detect a p		
	detection by design			• •	use of fail		
	control				bsequent	failure	
Almost certain	Design control will	1			ode. Or ther	e is no	
	almost certainly detect			de	sign control		
	a potential cause of						
	failure or subsequent		Adapted fr	om (Liu et a	1., 2013)		
	failure mode		-				
Very high	Very high chance the	2	2.2 ANA	LYSIS			
	design control will						
	detect a potential		1. Critical	ity Analysis			
	cause of failure or				s are focused	1 on critica	lity number
	subsequent failure				ng severity r		
	mode				ire mode. (
High	High chance the	3					
	design control will		failure mode usually ranks the potential of com risk of failure which is centered on the componen mode occurrence and consequence of the failure e				
	detect a potential						
	cause of failure or				low using the		
	subsequent failure				of failure mo		
	mode						F
Moderately high	Moderately high	4	TABLE 6: 1	PAYLOAD C	OMPONENTS	CRITICALIT	Y NUMBER
	chance the design		COMPUTAT	ION			
	control will detect a						-
	potential cause of		Part	Failure	Severity	Occurre	Criticalit
	failure or subsequent		Name	Mode	Number	nce	y
	failure mode					Number	Number
Moderate	Moderate chance the	5					
	design control will		Receiver C	Components	1	1	
	detect a potential			1			
	cause of failure or						
	subsequent failure						
T	mode		Input	Opening	3	1	3
Low	Low chance the design	6	Wavegui	of			
	control will detect a		de Filter	connectio			
	potential cause of						
	failure or subsequent			ns			
X 7 1	failure mode	-	Input Stee	l e Componen	te	1	1
Very low	Very low chance the	7	Input Stage	Componen	10		
	design control will						
	detect a potential						
	cause of failure or		Low	Innut	4	1	4
	subsequent failure			Input	-	1	1
Deverse	mode	0	Noise	signal t	.0		
Remote	Remote chance the	8	Amplifier	down			
	design control will	1	1	converter	.	1	1





(LNA)	distortion					tube or cathode			
	Unstable	4	1	4		camouc			
	input				CAMP	Failure of	4	1	4
	signal to					transpond			
	down					er			
	converter								
					Fixed	Interruptio	2	1	2
Down Con	verter		·	•	Amplifier	n of the			
Oscillator	Disorder	2	1	2		output			
Obelilator	in the	2	1	2		signal of			
	performan					down			
	-					converter			
					X /	To the surgery the	2	1	2
	down				Variable	Interruptio	2	1	2
	converter				Attenuator	n of the			
DLI	Г		1			output		1	
PLL	Frequency	2	1	2		signal of			
	intermissi					transmitte			
	on or					r			
	disorder								
	of output								
	signal								
						ents with cri			
Mixer	Power	2	1	2		high concern			
	loss in				that high power amplifier and component in the system are critica the satellite communication payload				
	output								
	signal of								
	mixer/					f these comp			
	increase in				mitigation n	of the active	compoi	ients of the	payload as
	the level				mitigation	leasures.			
	of				2 Diele Drie	ority Number			
	unwanted				2. NISK I I R	filly Number	(KIN)		
					DDN me	thad was the	aa mamlria	and to come	up with on
	signals					thod uses thr and these rar			
	Low	2	1	2		e occurrence			
	isolation	-		-		nd the probab			
	between					three are mea			
					then multipl	ied with one	another t	o get the RP	N value for
	the					onent in the			
	openings					s with a high			ed that, the
High Powe	r Amplifier				component	has high risk o	of failure		
TWTA	High	3	1	3					
1 11 171	-	5	1	5					
	output								
	power								
	Output	4	1	4					
	power loss								
	Failure of	4	1	4	_				
		7	1	-					
	TWTA								



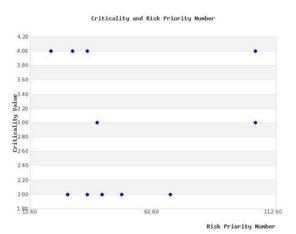


Part Name	Failure Mode	0	S	D	RPN	
Receiver Components						
Input	Opening of	3	7	5	105	
Waveguide	connections		<i>'</i>		105	
Filter	connections					
Input Stage C	omnonents				1	
Low Noise	Input signal to down	5	7	3	105	
Amplifier	converter distortion		, í		105	
(LNA)	Unstable input	4	9	1	36	
(21.11)	signal to down	.	Í	1		
	converter					
Down Conve		I			1	
Oscillator	Disorder in the	2	9	2	36	
	performance of					
	down converter					
PLL	Frequency	3	7	2	42	
	intermission or	_				
	disorder of output					
	signal					
Mixer	Power loss in output	2	7	2	28	
	signal of mixer/					
	increase in the level					
	of unwanted signals					
	Low isolation	2	7	5	70	
	between the					
	openings					
High Power A						
TWTA	High output power	4	10	1	40	
	Output power loss	3	10	1	30	
	Failure of TWTA	3	10	1	40	
	tube or cathode					
CAMP	Failure of	3	7	1	21	
	transponder					
Fixed	Interruption of	4	7	28		
Amplifier	output signal of					
	down converter					
Variable	Interruption of the	2	5	5	50	
Attenuator	output signal					

TABLE 7: RISK PRIORITY NUMBER COMPUTATION

TABLE 8: COMPONENT CRITICALITY AND RISK PRIORITY VALUES

Transponder Components	Components Criticality	Risk Priority Number		
Input	3	105		
wave guide				
filter				
Low	4	105		
Noise				
Amplifier 1				
Low	4	36		
Noise				
Amplifier 2				
Oscillator	2	36		
Phase	2	42		
Lock Loop				
(PLL)				
Mixer 1	2	28		
Mixer 2	2	70		
TWTA 1	3	40		
TWTA 2	4	30		
TWTA 3	4	30		
CAMP	4	21		
Fixed	2	28		
Amplifier				
Variable	2	50		
Attenuator				



From the RPN analysis it's found that input filter, LNA, mixer has higher value of risk priority and translate to higher chances of risk failure.

3. Correlation Analysis

To establish the association between criticality of component (reliability) and component failure risk priority. Component criticality value is the independent variable while component risk priority number is the





3 RESULTS AND DISCUSSION

From the analysis of criticality of components using MIL-STD-1628 for the analysis, it shows that Low Noise Amplifier and High Power Amplifier components has critical value (4) four, and it means that at single point failure of these components would result to catastrophic severity effects on the satellite system and this might result to the total loss of signal from the payload and the mission would be at risk of failure.

While the RPN analysis, considering the suggested ratings adopted by Liu et al in their research and the ECSS-Q-STD-30-02C of space product assurance failure modes. The result shows that the input wave guide filter, Low noise amplifier, mixer and variable attenuator has high value of risk priority number 105,105,70, and 50 respectively. Some components with high criticality values like low noise amplifier of input stage component, High Power Amplifier components' has low value for risk priority number. In essence, these components with high RPN value signified high priority of risk

Theoretically, it would be that high critical components should have high risk failure priority and the correlation coefficient should be strong. The factors responsible for that not to happen in this study, is that some components with high severity rankings have low detection and occurrence rankings while some components with lower severity rankings with higher value of detection and occurrence rankings and this would definitely have higher value of risk failure priority when these rankings are multiplied out.

The result of the correlation coefficient shows a weak association with a value of r = 0.0488 between critical components and risk of failure, it would be expected that components with high criticality value should have strong association with risk priority of failure.

4 CONCLUSION

Considering single point failure mode of the communication payload components in Table 2, from the four severity level of failure developed by MIL-STD-1628 and components with failure effect of causing complete component, system and mission lost has criticality value of (4) four. Components such as low noise amplifier of the input stage, high power amplifier components are of high criticality values as a result of the criticality analysis of the sample data collected for the study as shown in table 6 and it implies that any failure of these components would bring about mission lost.

To avert or mitigates the effect of single point failure of these active components, a redundancy or back- up components should be incorporated in the design such that at the event of failure of any active components the backup components would take active position to prevent total system failure.

The risk priority number, is similar to the criticality number, the difference is in computing for the criticality number to determine the critical components only the severity of failure and probability of failure occurrences are considered while in the risk priority number both the probability of failure mode, severity of failure effects and the probability of failure detection are computed.

Table 7 shows that components with high value of risk priority number are of high chances of failure, similar to criticality number. While performing correlation analysis to ascertain the association of criticality number and risk failure priority number, it shows a no correlation.

The study demonstrated that critical components are not necessary the components with high risk failure priority, in as much as components with high critical value are kept in watch likewise components with high risk failure priority number.

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